

SINGLE SENSOR SINGER/MUSIC SEPARATION USING A SOURCE/FILTER MODEL OF THE SINGER VOICE



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Introduction

- **Single-sensor singer/music separation:** separating the singer voice from the background polyphonic music on audio signals;
- **Proposed method:** applying a source/filter model to the vocal part and estimating its sequence of fundamental frequencies.

SYSTEM OUTLINE

1. **ML estimation of $a_r, a_{f_0}, \sigma_k, a_r, \sigma_r$:** multiplicative gradient approach,
2. **Melody line $F_0(t)$ inference:** Viterbi smoothing on $a_{f_0}(t)$ [1]
3. **Re-estimation of the parameters:** ML initialized with modified amplitude glottal source coefficients $\tilde{a}_{f_0}(t)$ such that $\forall t, \tilde{a}_{f_0}(t) = a_{f_0}(t)$, if $f_0 = F_0(t)$ and 0 otherwise.
4. **Computation of the separated signals \hat{v} and \hat{m} :** Wiener filters and Overlap-Add.

SIGNAL MODEL

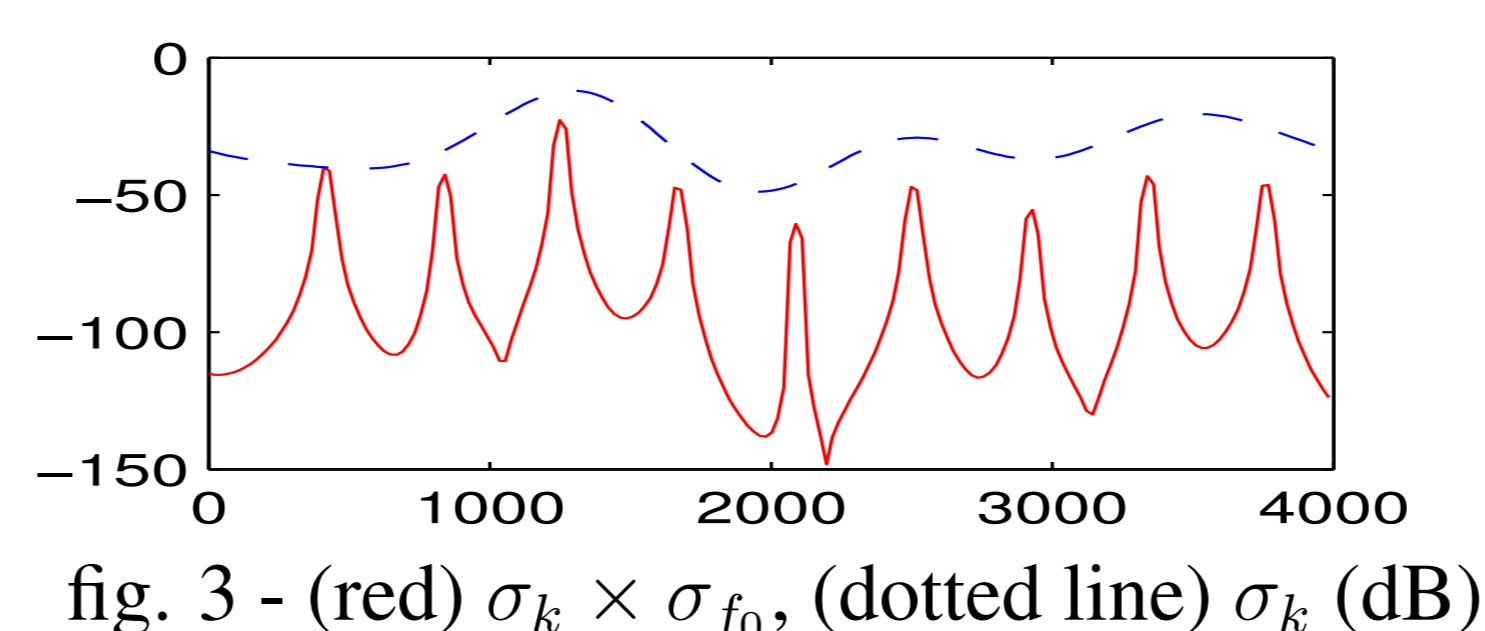
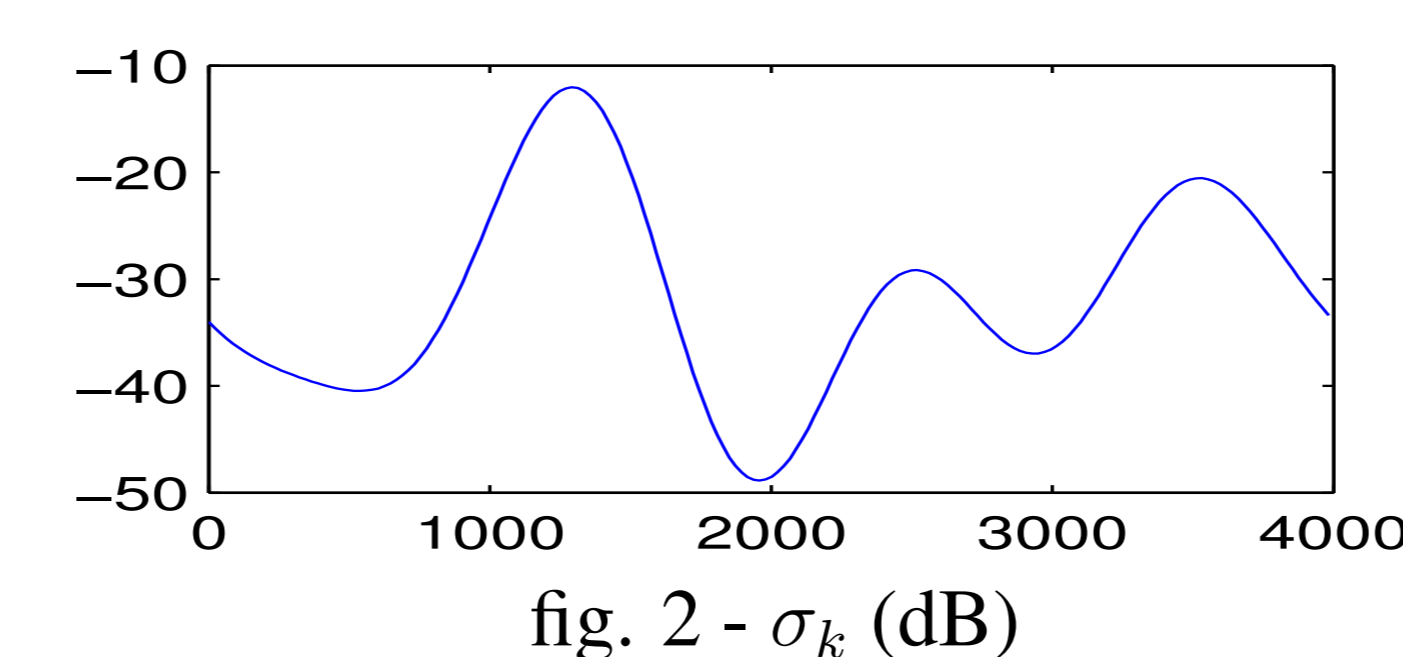
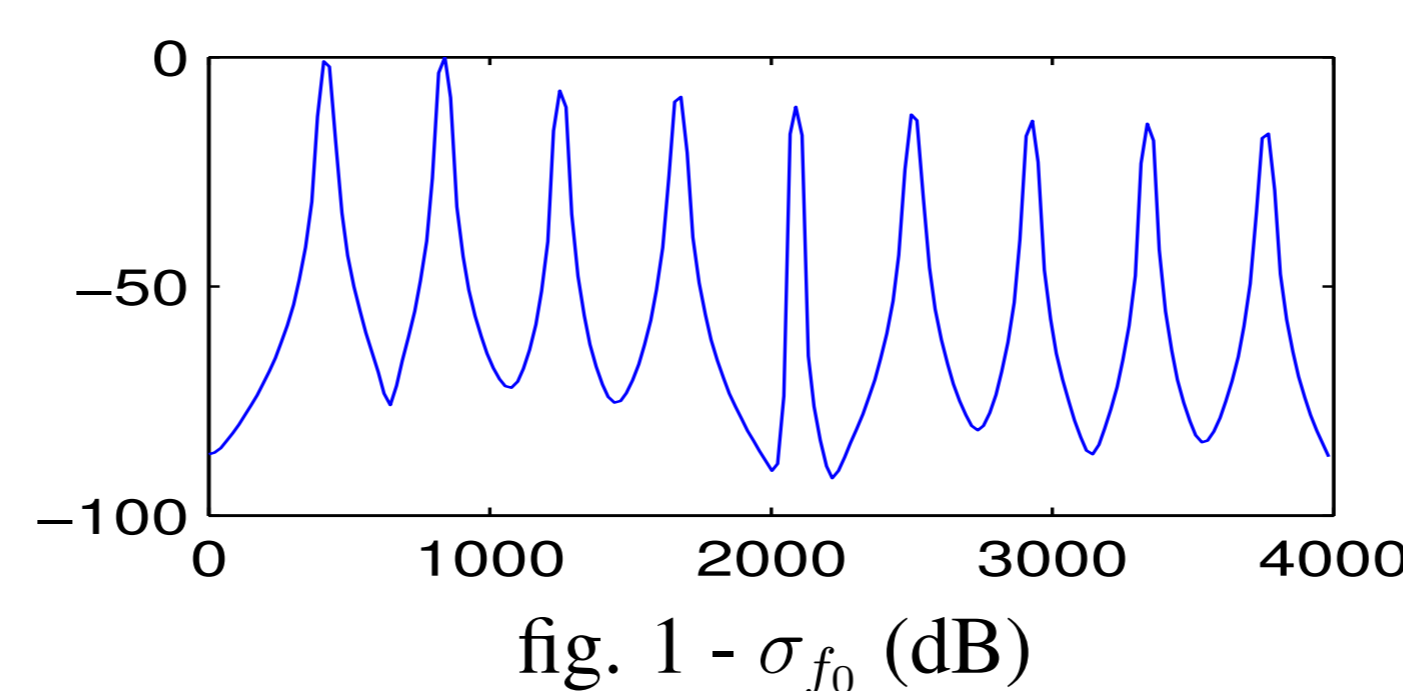
Assumptions on the signal:

- **2 sources:** singer voice v and background music m , observed signal x such that: $x = v + m$,
- **Wide sense (local) stationarity:** analysis based on the short time Fourier transform (STFT) X ,
- **Proper Gaussian** centered random variables: $Y \sim \mathcal{N}_c(0, \sigma_Y)$

Source/filter singer voice model

Source/Filter model for the voice:

- Dictionary of **fixed glottal source PSDs** σ_{f_0} (fig. 1),
 - KLGLOTT model: spectral “combs”
 - Fundamental frequencies between 100 and 800 Hz, 48 notes per octaves, $N_{\text{notes}} = 145$ combs,
 - No model for unvoiced part of singer signal,
 - $f_0 \in [1, N_{\text{notes}}]$.
- Dictionary of **vocal tract filters** σ_k (fig. 2),
 - Each σ_k characteristic of 1 vowel (in theory),
 - $K = 9$ filters to be estimated, $k \in [1, K]$,
 - No constraints on estimation of $\sigma_k \rightarrow$ not accurate.



- Resulting prototype **PSD of the voice** at frequency bin f , for a given source/filter couple (k, f_0) (fig. 3): $\sigma_k(f) \times \sigma_{f_0}(f)$

Instantaneous Mixture Model (IMM):

- $a_k(t)$ and $a_{f_0}(t)$ amplitude coefficients for filter k and source f_0 ,
- Each couple (k, f_0) always “active”.

$$V(f, t) \sim \mathcal{N}_c(0, \underbrace{\sum_k a_k(t) \sigma_k(f)}_{V_K(f,t)} \times \underbrace{\sum_{f_0} a_{f_0}(t) \sigma_{f_0}(f)}_{V_{F_0}(f,t)})$$

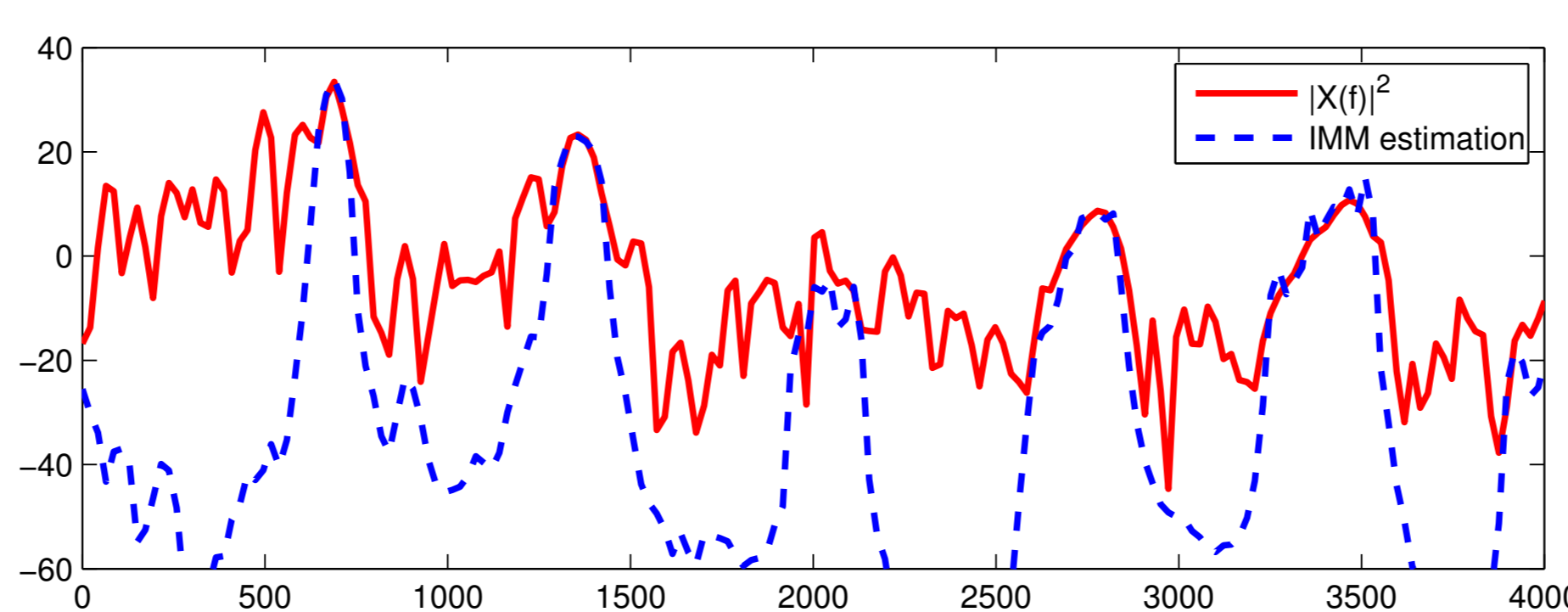
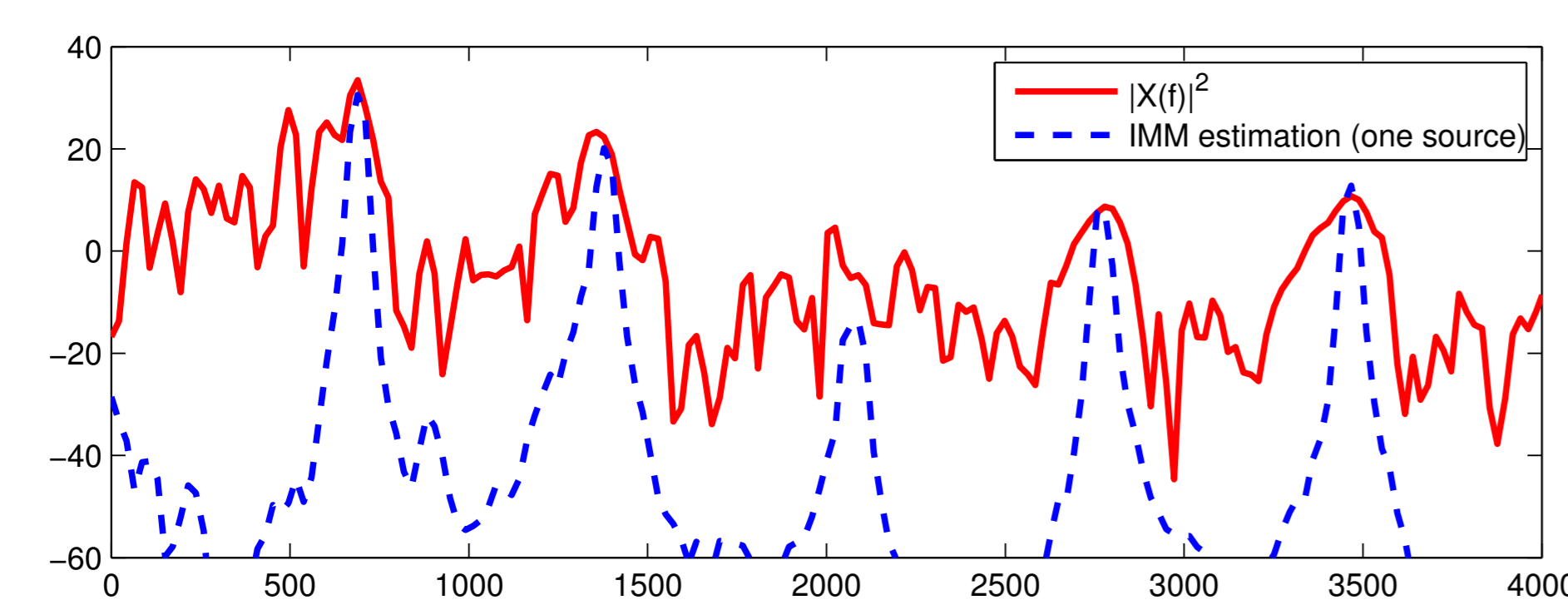


fig. 4 Frame of a singer “chirp” on polyphonic music: advantage of multiple-source model

Background music model

Instantaneous mixture of R Gaussian independent sources, with variances σ_r :

$$M(f, t) \sim \mathcal{N}_c(0, \underbrace{\sum_{r=1}^R a_r(t) \sigma_r(f)}_{D_R(f,t)})$$

Mixture signal

Instantaneous mixture of the two original sources: $X = V + M \Rightarrow$

$$X(f, t) \sim \mathcal{N}_c(0, D(f, t)) \text{ with: } D(f, t) = V_K(f, t) \times V_{F_0}(f, t) + D_R(f, t)$$

RESULTS

BSS EVAL criteria

- Different contributions in separated signals:

$$\hat{v} = \underbrace{\alpha_v v}_{e_{\text{target}}} + \underbrace{\beta_m m}_{e_{\text{interference}}} + e_{\text{artifact}}$$

- Normalized criteria computed from **Source-to-Distortion/Interference/Artifact-Ratio (SDR/SIR/SAR)**:

$$\text{SDR} = 20 \log_{10} \left(\frac{\|s_{\text{target}}\|}{\|e_{\text{interference}} + e_{\text{artifact}}\|} \right)$$

$$\text{SIR} = 20 \log_{10} \left(\frac{\|s_{\text{target}}\|}{\|e_{\text{interference}}\|} \right)$$

$$\text{SAR} = 20 \log_{10} \left(\frac{\|s_{\text{target}} + e_{\text{interference}}\|}{\|e_{\text{artifact}}\|} \right)$$

Synthetic data

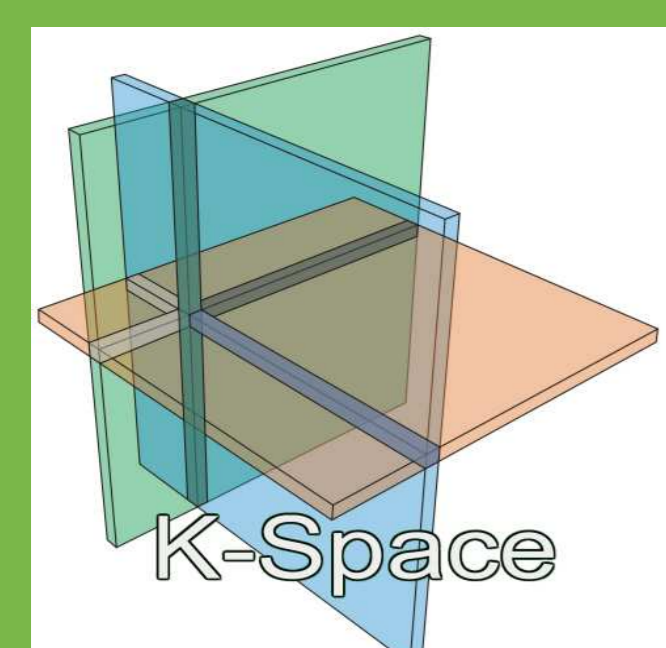
Synthesized audio from 200 MIDI files, melody played by an oboe:

	\hat{v}			\hat{m}		
	SDR	SIR	SAR	SDR	SIR	SAR
1st est.	10.04	24.34	8.76	7.51	15.48	12.45
2d est.	12.92	25.91	11.56	10.38	25.82	14.06

Real data

10 “pop” songs, with/without vocal/non-vocal segmentation [2]

	\hat{v}			\hat{m}		
	SDR	SIR	SAR	SDR	SIR	SAR
no vocal/non-vocal segmentation:						
1st est.	3.73	12.08	0.39	0.7	5.9	9.87
2d est.	6.42	14.82	2.37	1.58	12.78	8.44
manual v/n-v segmentation:						
1st est.	6.98	22.03	1.34	3.13	6.08	13.92
2d est.	10.71	25.01	4.93	5.66	13.96	12.81



Conclusions and Perspectives

- **Results at the state of the art**, with good perceptual results,
- IMM drawbacks balanced by **re-estimation of parameters**,
- **Bayesian framework** allowing model refinements: temporal and spectral regularization of the parameters, e.g. ARMA models on σ_k , HMM on $a_{f_0}(t)$ etc.